

$$T = \frac{1}{2} m v_G^2 + \frac{1}{2} I_G \omega^2$$

$$\vec{v}_G = (s-3l) \cos \theta \vec{e}_1 + 2l \dot{\theta} \vec{e}_2$$

$$\vec{v}_G = [\dot{s} \cos \theta - (s-3l) \sin \theta \dot{\theta}] \vec{e}_1 + [\dot{s} \sin \theta + (s-3l) \cos \theta \dot{\theta}] \vec{e}_2 \quad v_G^2 = \dot{s}^2 + (s-3l)^2 \dot{\theta}^2$$

$$I_G = \frac{1}{12} m 36l^2 = 3ml^2 \quad \omega = \dot{\theta}$$

$$T = \frac{1}{2} m (\dot{s}^2 + (s-3l)^2 \dot{\theta}^2) + \frac{3}{2} ml^2 \dot{\theta}^2 = \frac{1}{2} m \dot{s}^2 + \frac{1}{2} m (s^2 - 6ls + 12l^2) \dot{\theta}^2$$

$$V_F = -4mgl \int_s^6 \frac{ds'}{s'} - 4mgl \int_s^{6l-s} \frac{ds'}{s'} = -4mgl [\log s + \log(6l-s)] + \text{cost}$$

$$V_P = mgy_G = mg(s-3l) 2\sin \theta$$

$$V = V_F + V_P = -4mgl [\log s + \log(6l-s)] + mg(s-3l) 2\sin \theta$$

$$L = \frac{1}{2} m \dot{s}^2 + \frac{1}{2} m (s^2 - 6ls + 12l^2) \dot{\theta}^2 - mg(s-3l) 2\sin \theta + 4mgl (\log s + \log(6l-s))$$

$$m\ddot{s} - m(s-3l)\dot{\theta}^2 - \frac{4mgl}{s} + \frac{4mgl}{6l-s} + mg 2\cos \theta = 0$$

$$m(s^2 - 6ls + 12l^2)\ddot{\theta} + 2m(s-3l)\dot{s}\dot{\theta} + mg(s-3l)\cos \theta = 0$$

$$\frac{\partial V}{\partial \theta} = mg(s-3l) \cos \theta = 0$$

$$\frac{\partial V}{\partial s} = +mg \left( -\frac{4l}{s} + \frac{4l}{6l-s} + 2\sin \theta \right) = 0$$

$$s \geq 0; s \leq 3l \text{ o } \cos \theta = 0 \quad (\text{con } 0 \leq s \leq 6l)$$

$$1) s=3l, \theta=0 \quad 2) s=3l, \theta=\pi \quad 3) s=2l, \theta=\frac{\pi}{2} \quad 4) s=4l, \theta=\frac{\pi}{2}$$

$$5) s=4l, \theta=-\frac{\pi}{2} \quad 6) s=-6l, \theta=-\frac{\pi}{2}$$

$$\frac{\partial^2 V}{\partial \theta^2} = -mg(s-3l) \sin \theta$$

$$\frac{\partial^2 V}{\partial s^2 \partial \theta} = mg \cos \theta$$

$$\frac{\partial^2 V}{\partial s^2} = 4mgl \left( \frac{1}{s^2} + \frac{1}{(6l-s)^2} \right) > 0$$

$$V_{ss} > 0 \text{ sempre} \quad H = -m^2 g^2 \left[ \left( \frac{1}{s^2} + \frac{1}{(6l-s)^2} \right) (s-3l) \sin \theta + \cos 2\theta \right]$$

$$H > 0 \text{ per } s=2l, \theta=\frac{\pi}{2} \text{ o } s=4l, \theta=-\frac{\pi}{2}$$

$$\text{in } s=2l, \theta=\frac{\pi}{2} \quad T \sim \frac{m}{2} (\dot{s}^2 + 4l^2 \dot{\theta}^2)$$

$$A = \begin{pmatrix} m & 0 \\ 0 & 4me^2 \end{pmatrix}$$

$$C = \begin{pmatrix} \frac{5}{4} mg & 0 \\ 0 & mgl \end{pmatrix}$$

$$h_1 = \frac{5}{4} \frac{g}{e}$$

$$h_2 = \frac{1}{4} \frac{g}{e}$$

moti traslatori re  $\dot{\theta} = \ddot{\theta} = 0$ . Dalle eq. di Lagrange segue  $\cos \theta = 0$

$$\text{e } m\ddot{s} - \frac{4mgl}{s} + \frac{4mgl}{6l-s} \pm mg = 0 \quad \text{OK}$$