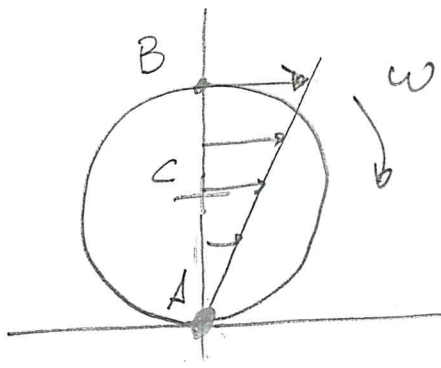
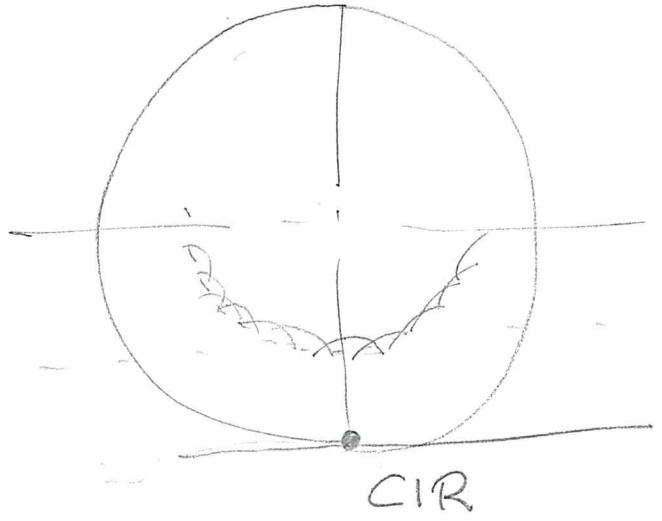
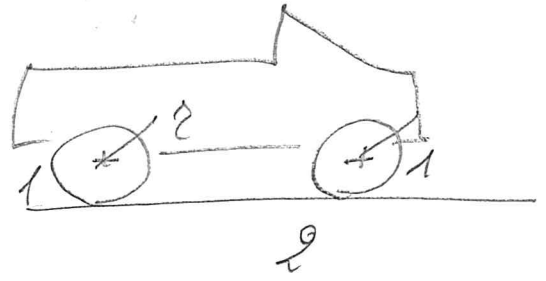
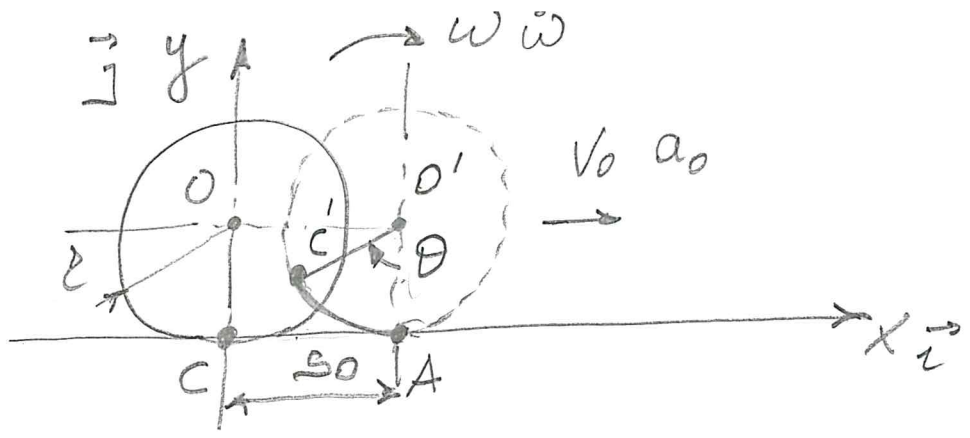


1 28.09.2016



$$V_B = \omega 2r$$





$$\vec{s}_0 = r \vartheta \vec{i}$$

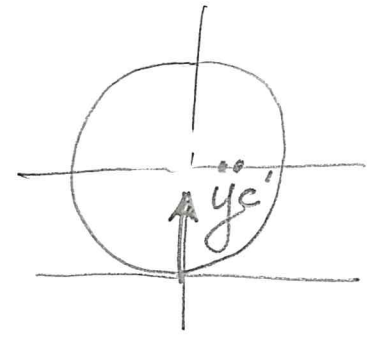
$$\vec{v}_0 = \frac{d\vec{s}_0}{dt} = r \dot{\vartheta} \vec{i} = r \omega \vec{i}$$

$$\vec{a}_0 = \frac{d\vec{v}_0}{dt} = r \ddot{\vartheta} \vec{i} = r \dot{\omega} \vec{i}$$

$$\begin{cases} x_{c'} = s_0 - r \sin \vartheta = r (\vartheta - \sin \vartheta) \\ y_{c'} = r - r \cos \vartheta = r (1 - \cos \vartheta) \\ \dot{x}_{c'} = r (\dot{\vartheta} - \dot{\vartheta} \cos \vartheta) = r \dot{\vartheta} (1 - \cos \vartheta) \\ \dot{y}_{c'} = r \dot{\vartheta} \sin \vartheta \\ \ddot{x}_{c'} = r \ddot{\vartheta} (1 - \cos \vartheta) + r \dot{\vartheta}^2 \sin \vartheta \\ \ddot{y}_{c'} = r (\ddot{\vartheta} \sin \vartheta + \dot{\vartheta}^2 \cos \vartheta) \end{cases}$$

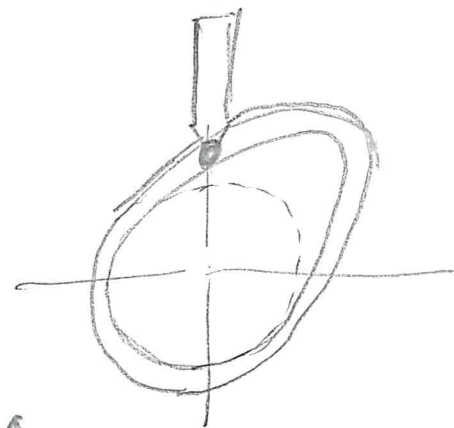
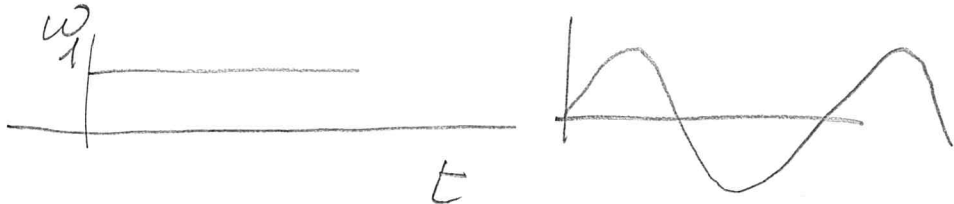
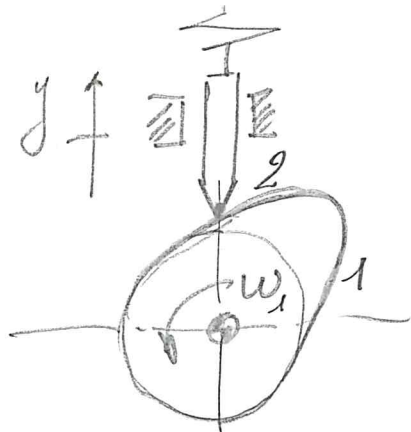
$C = C' \quad \vartheta = 0$

$$\begin{matrix} x_{c'} = 0 & y_{c'} = 0 \\ \dot{x}_{c'} = 0 & \dot{y}_{c'} = 0 \\ \ddot{x}_{c'} = 0 & \ddot{y}_{c'} = r \dot{\vartheta}^2 \end{matrix}$$

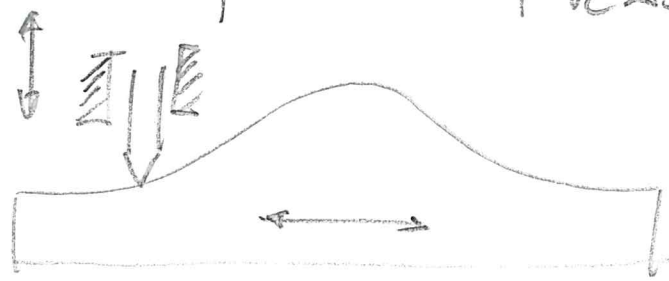


ROTATORIO - TRASLATORIO

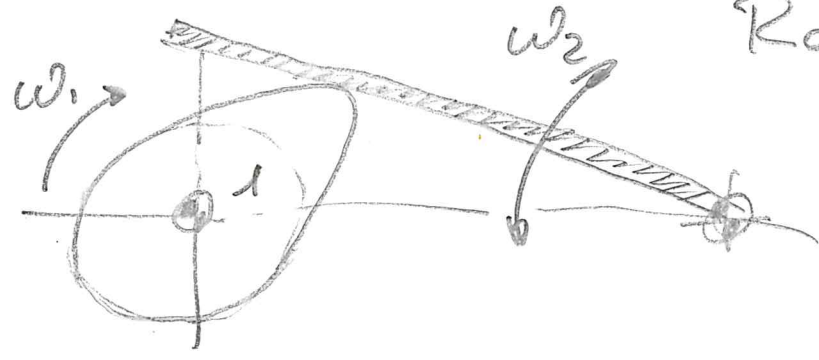
1 CAMMA MOVENTE
2 FUNERIA CEDENTE



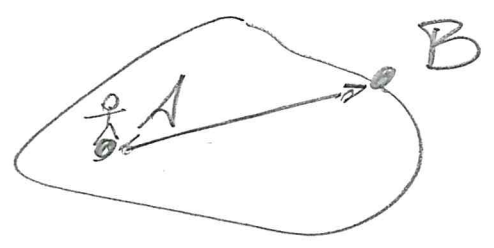
TRASLATORIO - TRASLATORIO



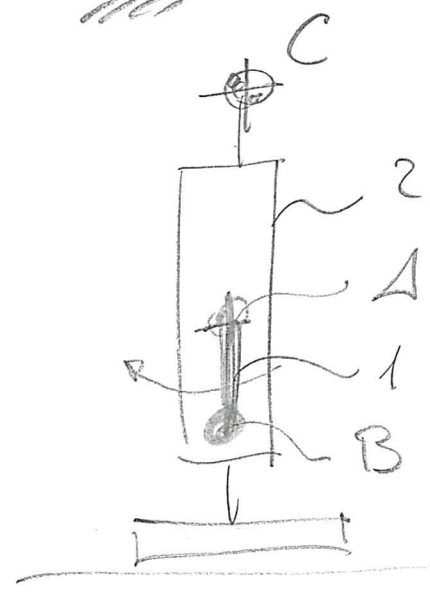
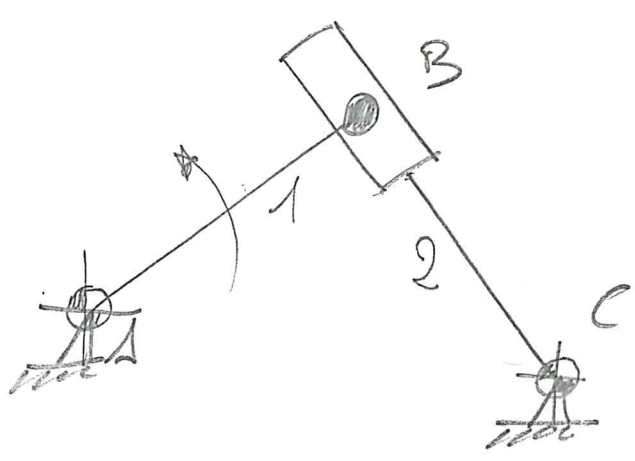
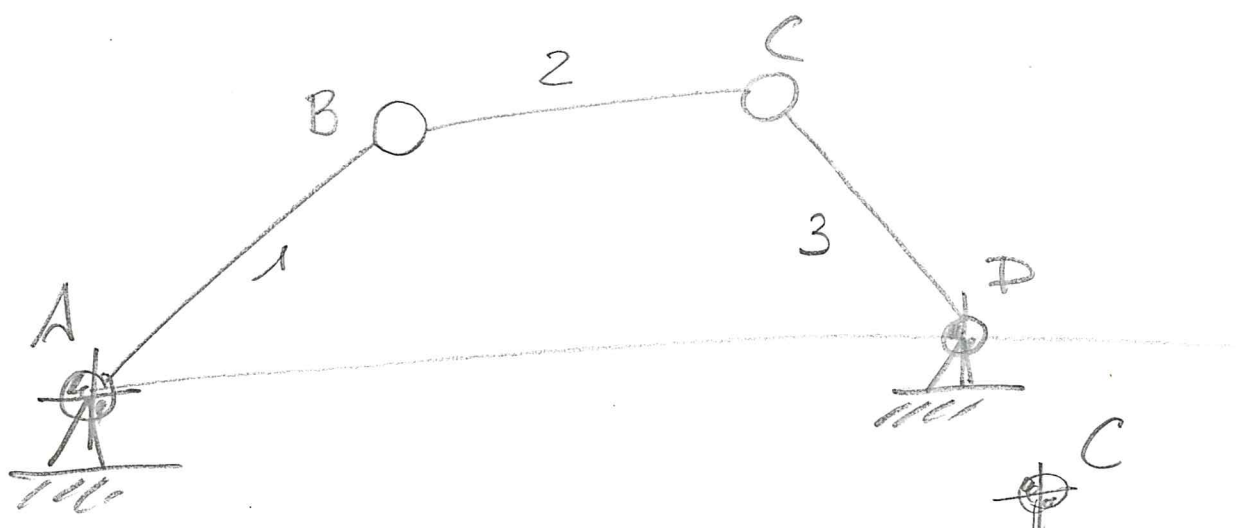
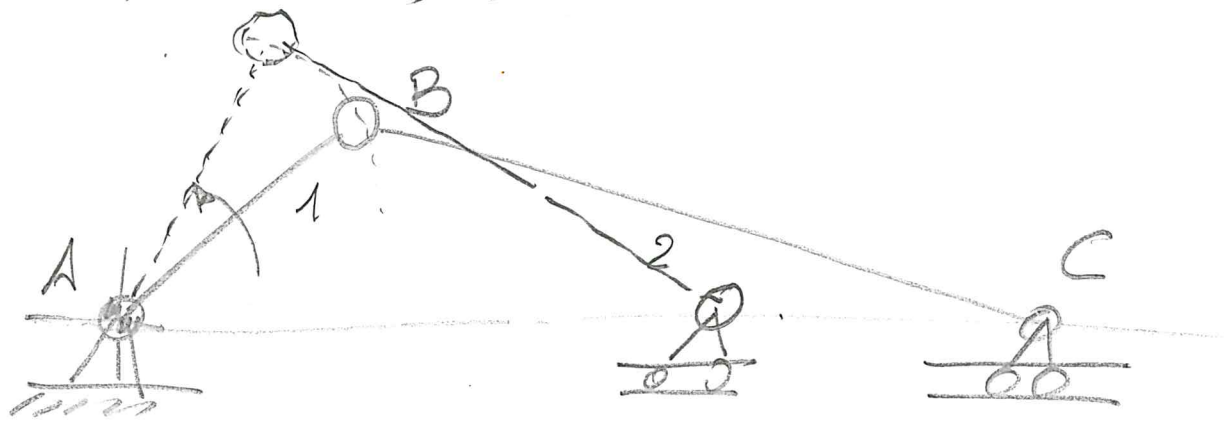
ROTATORIO - ROTATORIO



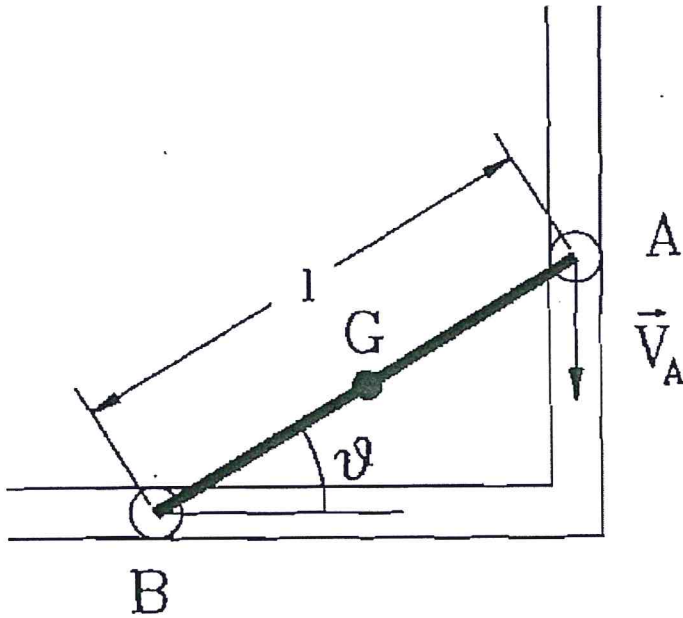
* $\vec{V}_B = \vec{V}_A + \vec{V}_{B/A}$ GALILEO
 $\vec{V}_{B/A} = \vec{\omega} \wedge \vec{AB}$



* $\vec{a}_B = \vec{a}_A + \vec{a}_{B/A}$ RIVALS
 $\vec{a}_{B/A} = \vec{a}_{B/A})_m + \vec{a}_{B/A})_t$



La barretta rigida AB, di lunghezza $l=200\text{ mm}$, ha le estremità che scorrono in due guide ortogonali. L'estremità A ha una velocità costante verso il basso di 2 m/s . Determinare, nell'istante in cui $\vartheta = 30^\circ$, la velocità angolare della barretta, la velocità del punto medio G (V_G) e la sua accelerazione a_G .

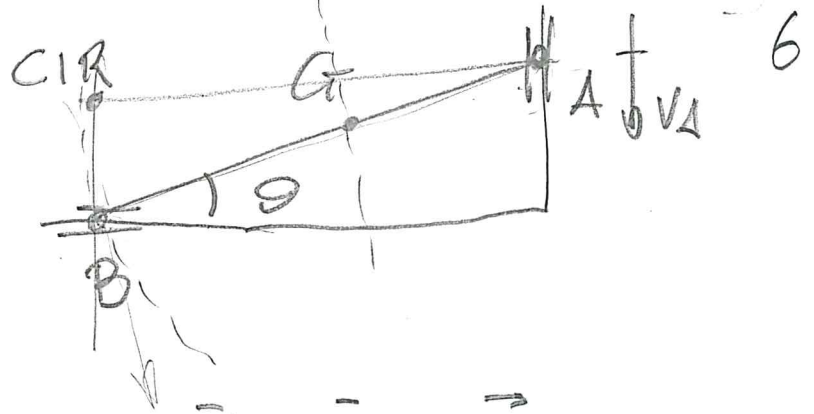


$$AB = l = 0,2 \text{ m}$$

$$V_A = 2 \text{ m/s}$$

$$\vartheta = 30^\circ$$

ω V_G a_G

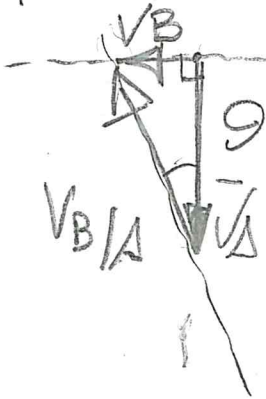


$$\vec{V}_B = \vec{V}_A + \vec{V}_{B/A}$$

?	2 m/s	ωAB	μ
$\parallel x$	$\parallel y$	$\perp AB$	\perp
?	\downarrow	?	\perp

$$\vec{V}_G = \vec{V}_A + \vec{V}_{G/A}$$

?	2 m/s	ωAG	μ
?	$\parallel y$	$\perp AG$	\perp
?	\downarrow	?	\perp



$$V_{B/A} = \frac{V_A}{\cos \vartheta}$$

$$\omega = \frac{V_{B/A}}{l} (-\vec{k})$$

$$\omega = 11,5 \frac{\text{rad}}{\text{s}}$$



$$V_{G/A} = \omega AG = 1,15 \text{ m/s}$$

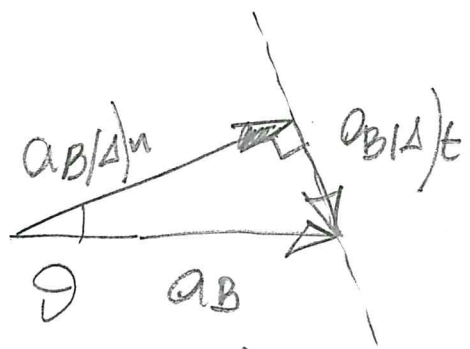
$$V_G = \sqrt{V_A^2 + V_{G/A}^2 - 2V_A V_{G/A} \cos \vartheta} = 1,157 \text{ m/s}$$

$$\vec{a}_B = \vec{a}_A + \vec{a}_{B/A)n} + \vec{a}_{B/A)t}$$

?	0	$\omega^2 \cdot l$ 26,45	$\dot{\omega} \cdot l$	u
//x	✓	//AB	⊥AB	D
?	✓	B → A	?	v

$$\vec{a}_G = \vec{a}_A + \vec{a}_{G/A)n} + \vec{a}_{G/A)t}$$

				u
				D
				v

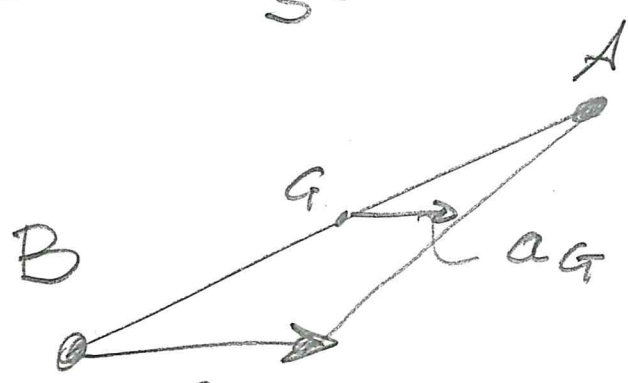


$$a_B = \frac{a_{B/A)n}}{\cos \theta} = 30,6 \text{ m/s}^2$$

$$a_{B/A)t} = a_{B/A)n} \cdot \tan \theta = 15,27 \frac{\text{m}}{\text{s}^2}$$

$$\dot{\omega} = \frac{a_{B/A)t}}{l} = 152,7 \frac{\text{rad}}{\text{s}^2} (+\vec{k})$$

$$\frac{a_G}{AG} = \frac{a_B}{AB}$$

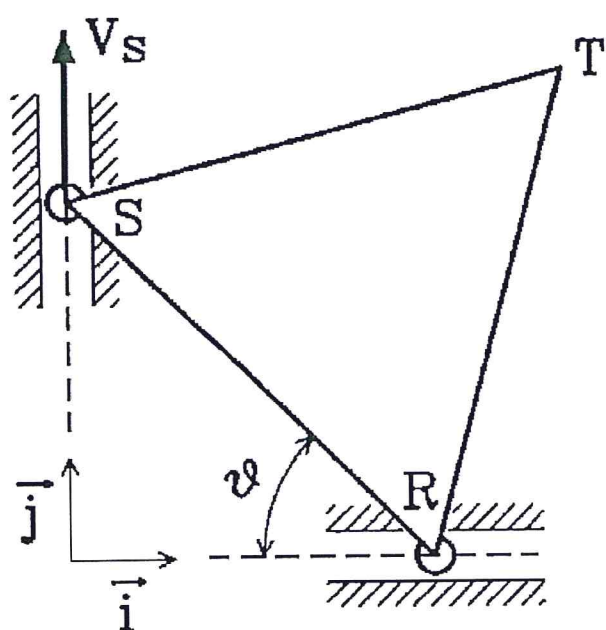


$$a_G = \frac{a_B}{2} = 15,3 \text{ m/s}^2$$

Il corpo rigido RST ha la forma di un triangolo equilatero, di lato $l=0,5 \text{ m}$. I vertici R e S sono vincolati a scorrere lungo due guide prismatiche ortogonali.

E' assegnata al vertice S una velocità costante pari a $0,8 \text{ m/s}$ nel verso indicato in figura.

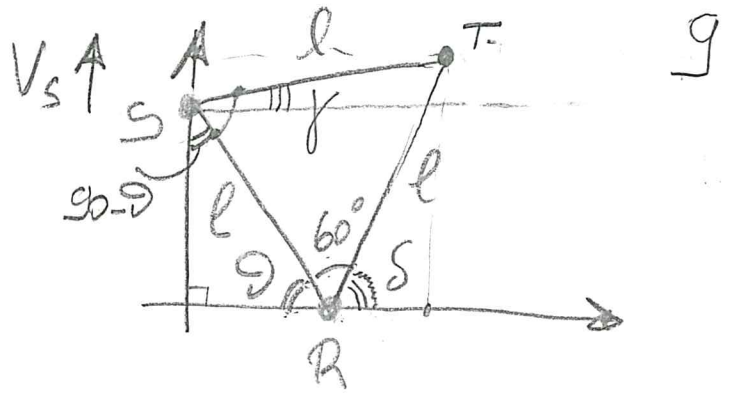
Calcolare per quale valore di ϑ la velocità di T ha componente verticale nulla. Con ϑ pari al valore calcolato, determinare la velocità del punto T e l'accelerazione del punto R.



$$V_S = 0,8 \text{ m/s} \cos t$$

$$l = 0,5 \text{ m}$$

$$\frac{d}{dt} V_{yT} = 0$$



$$\gamma = [(90 - \theta) + 60] - 90 = 60 - \theta$$

$$\delta = 180 - 60 - \theta = 120 - \theta$$

$$x_T = l \cos \gamma = l \cos(60 - \theta)$$

$$y_T = l \sin \delta = l \sin(120 - \theta)$$

$$\dot{x}_T = -l \sin(60 - \theta)(-\dot{\theta}) = l \dot{\theta} \sin(60 - \theta)$$

$$\dot{y}_T = l \cos(120 - \theta)(-\dot{\theta}) = -l \dot{\theta} \cos(120 - \theta)$$

$$\dot{y}_T = 0 \quad \dot{\theta} = 0 \quad \cos(120 - \theta) = 0 \quad 120 - \theta = 90 \quad \theta = 30^\circ$$

$$x_C = l \cos 30^\circ = 0,216 \text{ m}$$

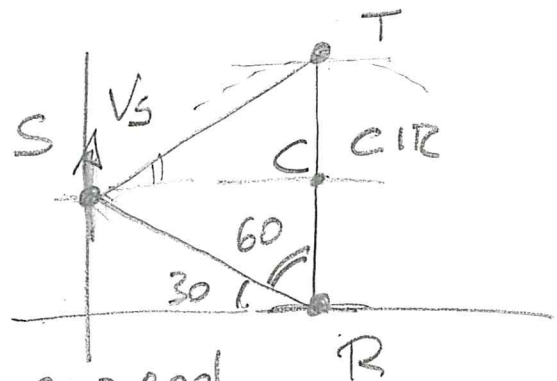
$$y_C = l \sin 30^\circ = 0,250 \text{ m}$$

$$CS = l \sin 60^\circ = 0,433 \text{ m}$$

$$V_S = \omega CS; \quad \omega = \frac{V_S}{CS} = 1,847 \frac{\text{rad}}{\text{s}}$$

$$\dot{x}_T \Big|_{\theta=30^\circ} = l \dot{\theta} \sin 30^\circ = 0,462 \text{ m/s}$$

$$\dot{y}_T \Big|_{\theta=30^\circ} = 0$$

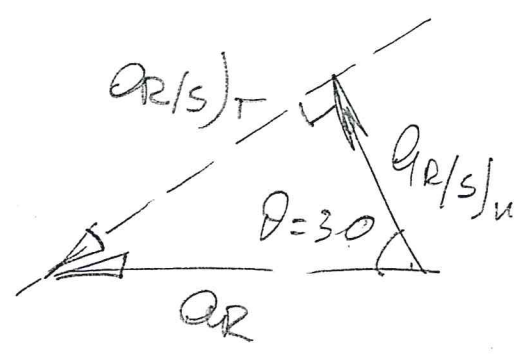


$$a_T = a_S + a_{T/S}_n + a_{T/S}_T$$

M	?	0	$\dot{\theta}^2 l$ 1,706	$\ddot{\theta} l$
D	?	✓	∥ TS	⊥ TS
V	?	✓	T → S	?

$$a_R = a_S + a_{R/S}_n + a_{R/S}_T$$

M	!	0	$\dot{\theta}^2 l$ 1,706	$\ddot{\theta} l$?
D	∥ X	✓	∥ RS	⊥ RS
V	?	✓	R → S	?



$$a_{R/S}_T = a_{R/S}_n \operatorname{tg} \vartheta = 0,98 \text{ m/s}^2$$

$$\ddot{\theta} = \frac{a_{R/S}_T}{l} = 1,97 \text{ rad/s}^2$$

DA $x_T = \dots$
 $x_T = \dots$

$$\begin{cases} \ddot{x}_T = l \ddot{\theta} \sin(60 - \vartheta) - l \dot{\theta}^2 \cos(60 - \vartheta) \\ \ddot{y}_T = -l \ddot{\theta} \cos(120 - \vartheta) + l \dot{\theta}^2 \sin(120 - \vartheta) \end{cases}$$

si HA com $\ddot{\theta} = 1,97 \text{ rad/s}^2$

$$\ddot{x}_T = -0,98 \text{ m/s}^2$$

$$\ddot{y}_T = -1,706 \text{ m/s}^2$$