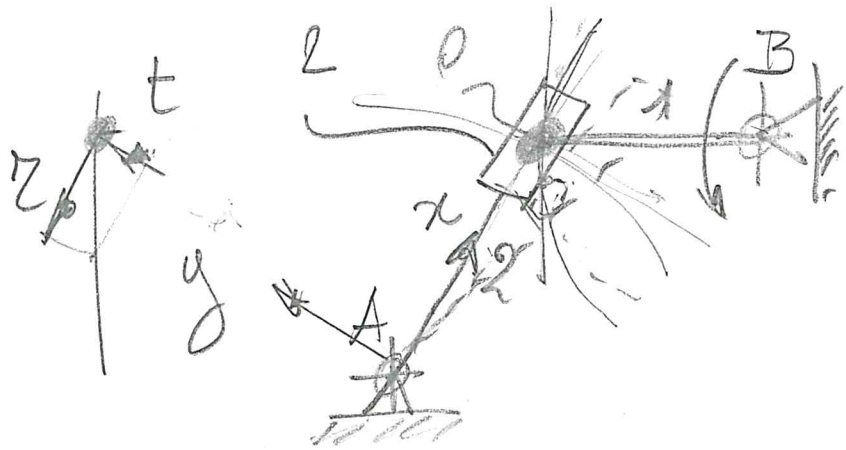
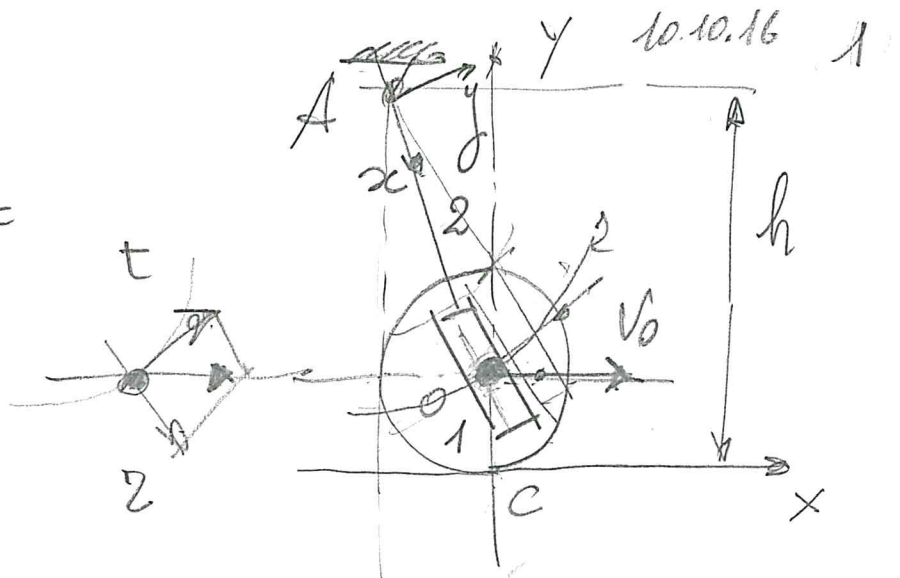


$$\vec{V}_0 = \vec{V}_r + \vec{V}_t$$

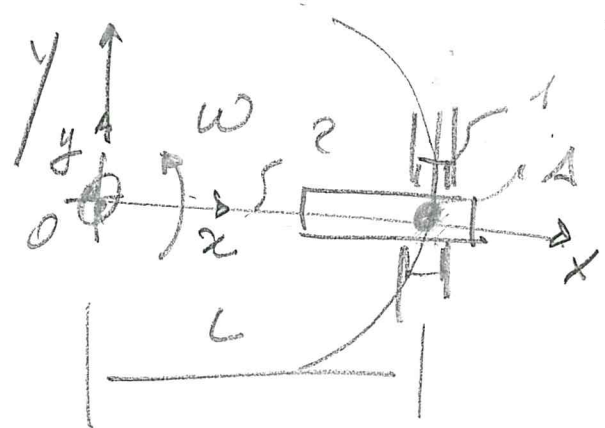


$L = 200 \text{ mm}$

$\omega = 1 \text{ rad/s (const)}$

$V_A \text{ ?}$

$\theta = 0^\circ$



$\vec{V}_A = \vec{V}_{A2} + \vec{V}_{A1}$

ω	?	?	ωOA $0,2 \text{ m/s}$
D	//	OA	$\perp OA$
V	?	?	\uparrow

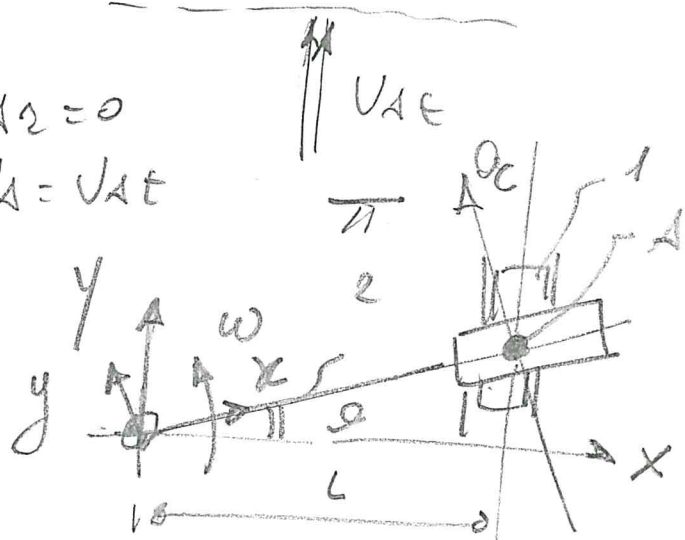
$\theta = 20^\circ$

$V_A = V_{A2} + V_{A1}$

ω	?	?	ωOA $0,21 \text{ m/s}$
D	//	OA	$\perp OA$
V	?	?	\uparrow

$V_{A2} = 0$

$V_A = V_{A1}$



$OA = L / \cos \theta = 0,21 \text{ m}$



$V_{A1} = V_{A2} \tan \theta$

$V_A = V_{A1} / \cos \theta$

$V_{A2} = 0,076 \text{ m/s}$

$V_A = 0,22 \text{ m/s}$

$\omega = \text{const}$
 a_A, a_{A2} ?

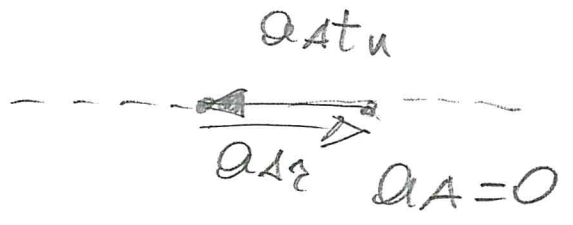
$\vartheta = 0^\circ$

$\bar{a}_c = 2\bar{\omega} \wedge \bar{v}_c$

$$\bar{a}_A = \bar{a}_{A2} + \bar{a}_{(A)M} + \bar{a}_{(A)E} + \bar{a}_c$$

M	?	?	ω^{20A} $0,2 \text{ m/s}^2$	$\dot{\vartheta}^{20A} = 0$	0
D	// Y	// OA	// OA	$\perp OA \quad \nabla$	∇
V	?	?	$A \rightarrow 0$	∇	∇

$\bar{a}_A = 0$
 $\bar{a}_{A2} = -\bar{a}_{(A)M} = 0,2 \text{ m/s}^2$



$\vartheta = 20^\circ$

$\bar{a}_c = 2\bar{\omega} \wedge \bar{v}_c$

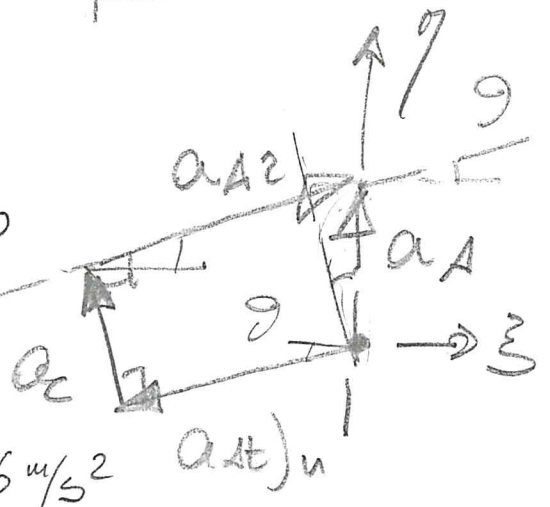
$$\bar{a}_A = \bar{a}_{A2} + \bar{a}_{(A)M} + \bar{a}_{(A)E} + \bar{a}_c$$

M	?	?	ω^{20A} $0,21 \text{ m/s}^2$	$\dot{\vartheta}^{20A} = 0$	$0,152 \text{ m/s}^2$
D	// Y	// OA	// OA	$\perp OA \quad \nabla$	$\perp OA \quad \nabla$
V	?	?	$A \rightarrow 0$	∇	∇

$$\begin{cases} -a_{(A)M} \cos \vartheta - a_c \sin \vartheta + a_{A2} \cos \vartheta = 0 \\ -a_{(A)M} \sin \vartheta + a_c \cos \vartheta + a_{A2} \sin \vartheta - a_A = 0 \end{cases}$$

$a_{A2} = \frac{1}{\cos \vartheta} (a_{(A)M} \cos \vartheta + a_c \sin \vartheta) = 0,26 \frac{\text{m}}{\text{s}^2}$

$a_A = -a_{(A)M} \sin \vartheta + a_c \cos \vartheta + a_{A2} \sin \vartheta = 0,16 \frac{\text{m}}{\text{s}^2}$



3D GRADI DI LIBERTA' CORPO RIGIDO 6

4

2D " " " " " 3

Vincoli

INCASTRATO

-3



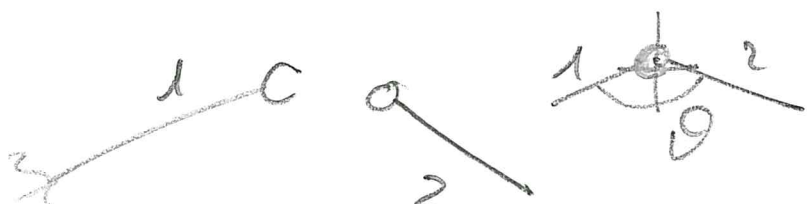
COPPIA ROTAZIONALE

-2



COPPIA ROT. 2 CORPI

-2



$u_1 = u_2$ $D_1 = \text{LIBERO}$
 $v_1 = v_2$ $D_2 =$

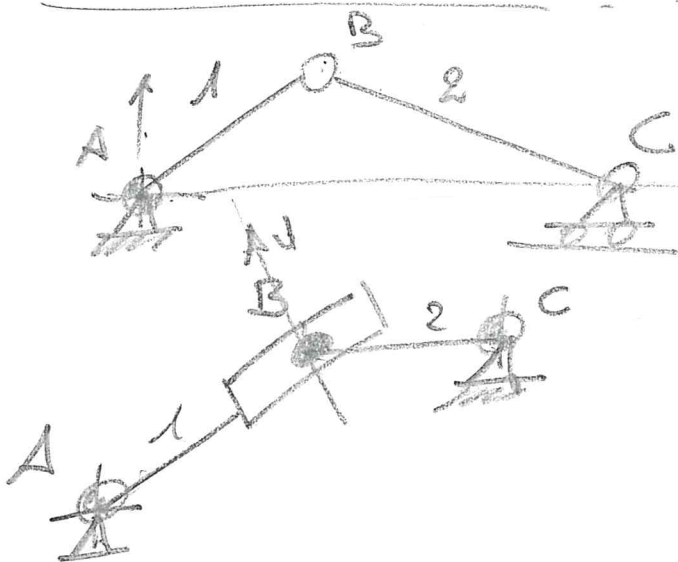
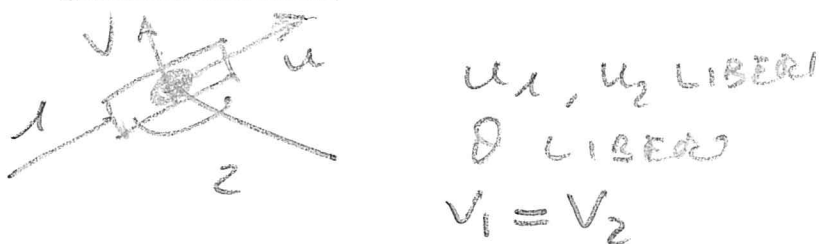
SLITTA-CARRELLI

-1



SLITTA

-1



6 GDL 2x3 6 GDL

$u_A = 0$ $v_A = 0$

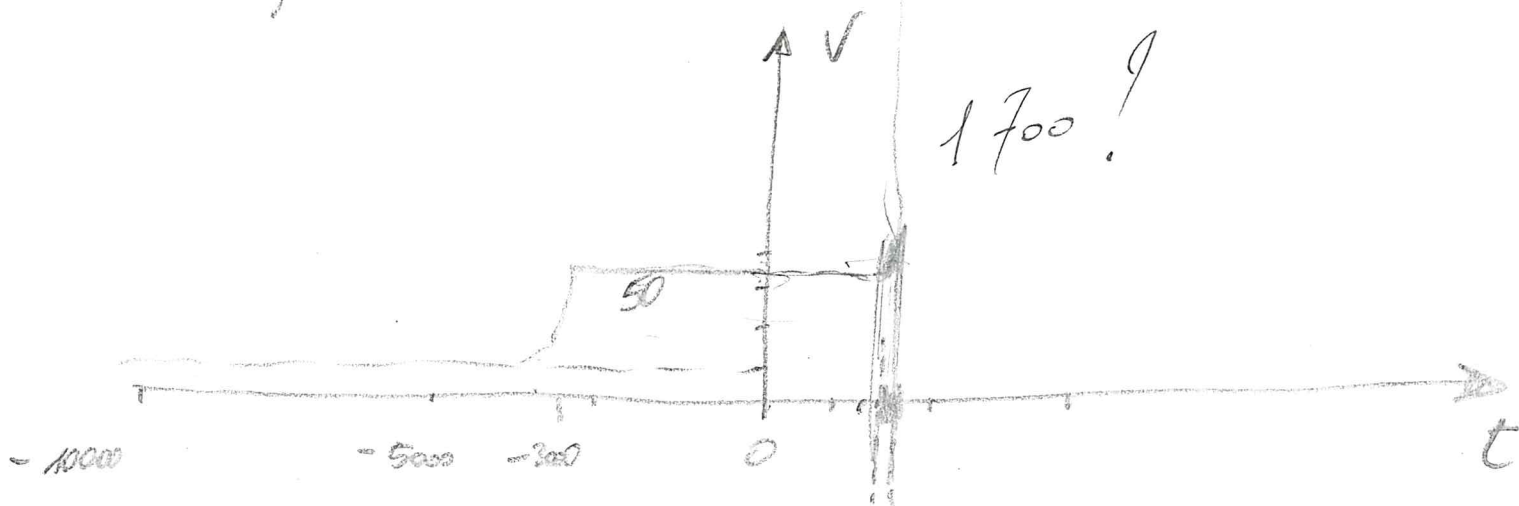
$u_B = u_{B_1} = u_{B_2}$ $v_{B_1} = v_{B_2}$

$v_C = 0$

6 GDL

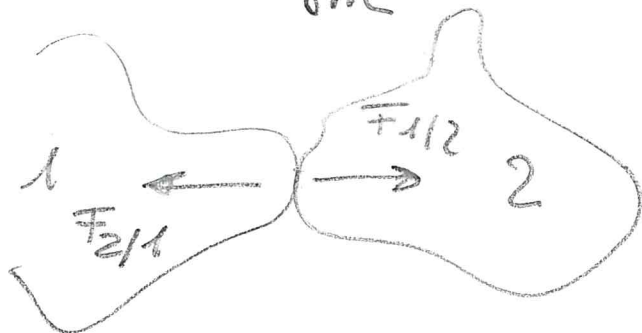
1 GDL

Σύνοψη ΔΥΝΑΜΙΚΑ



GALILEO
NEWTON

$$\vec{a} = \frac{\vec{F}}{m}$$



D'ALMBERT $\vec{F}_e + \vec{F}_i = \vec{0}$ $\vec{F}_i = -m\vec{a}$

$$\vec{F} = m\vec{a} ?$$